

## Topology Optimization Method for Nuclear Magnetic Resonance Logging tool Magnetic and Soft magnetic Design

<u>Qiao Zhen<sup>a,b</sup></u>, Luo Sihui <sup>a.b</sup>, Xiao Lizhi<sup>a,b</sup>, Liao Guangzhi<sup>a,b</sup>

<sup>1</sup> Key Laboratory of Petroleum Resources and Engineering, China University of Petroleum, Beijing, China; <sup>2</sup>China University of Petroleum, Beijing 102249, China;

Introduction: Nuclear magnetic resonance logging is an important part of petroleum exploration, and the design of the NMR probe magnet, antenna, and soft magnetic material is related to the accuracy of downhole reservoir detection. Traditional probe design is often based on empirical structures, which reduces the accuracy of matching the probe magnet and antenna, increases the cost of manual optimization (time and effort).

Methods: This study uses the Finite Element Method to effectively solve the  $B_0$  and  $B_1$  magnetic fields. In order to optimize the antenna and magnetic field at the same time, two magnetic fields are set and the design variables are derived separately by the chain rule:

$$\iint_{\Omega} V(\frac{\partial A_{Z}}{\partial_{X}} \frac{\partial A_{Z}}{\partial_{X}} + \frac{\partial A_{Z}}{\partial_{X}} \frac{\partial A_{Z}}{\partial_{X}}) dx dy = \iint_{\Omega} V(\frac{\partial A_{Z}}{\partial_{X}} \frac{\partial A_{Z}}{\partial_{X}} + \frac{\partial A_{Z}}{\partial_{X}} \frac{\partial A_{Z}}{\partial_{X}}) dx dy + \iint_{\Omega} J_{Z} N dx dy$$

N is the basis function, and  $A_Z$  is the magnetic vector potential.

We have divided the construction of magnets, antennas, soft magnetics, topology optimization and air domain into separate parts. The objective function, point distribution and constraints are as follows:

Find: 
$$\rho = (\rho_1, \rho_2, \rho_N)$$

Maximize: 
$$\phi = \sum_{i=1}^{100} B_{0, i}^2 \bullet (B_{1m}/I)$$

Subject to:  $0 \le \rho_e \le 1$ 

The density interpolation model of SIMP interpolation function is used for density interpolation. The finite element material interpolation function is:

$$\mu(\rho_{\rm e}) = \mu_0 + \theta_{\rm p} \bullet (\mu_i \bullet \mu_0 - \mu_0)$$

 $\mu_0$  is the magnetic permeability of air, and  $\mu_i$  is the permeability of soft magnetic material.

The model is iteratively solved using the moving asymptote method (MMA) based on gradient descent.

Results and discussion: The magnet volume is reduced by 10%, 30%, and 60%, the resulting magnetic field strength decreases accordingly. To generate the maximum magnetic field, the entire magnet volume is selected as the primary magnet. The soft magnetic material, after topology optimization,

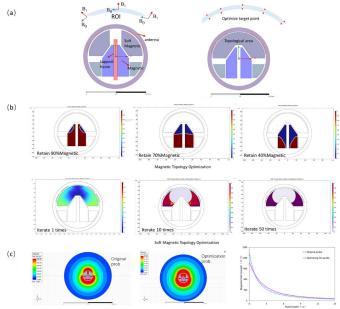


Fig. 1: (a) illustrates the optimization objective and the optimization domain. (b) shows the topology-based optimization of the magnet and the soft magnetic material. (c) presents the optimization results.

exhibits a horn-shaped structure. The sensitive region is located 5–7 cm outside the magnet. and it can generate a static magnetic field with an intensity of  $114.6 \sim 157.8$ G and a gradient of  $273.0 \sim 165$ G/cm in the distal ROI as illustrated in **fig** (c).

References: [1] Gregor, Sci. Rep. (2022) .

[2] Deaton, Struct Multidiscip O. (2014).